

	L #	Hits	Search Text	DBs	Time Stamp
1	L1	2525	((object\$1 or obstacle\$1) near3 (detect\$3 or sens\$3 or scan\$4)) near5 radar	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 06:57
2	L2	29248	(calculat\$3 or obtain\$3 or determin\$3) near5 ((object\$1 or obstacle\$1) near3 (position\$1 or location\$1 or point\$1 or data))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 06:57
3	L3	54	((estimat\$3 or determin\$3 or calculat\$3 or predict\$3 or projec\$3) near5 ((position or location) near3 (object\$1 or obstacle\$1))) near10 ((previous\$2 or prior or past) near3 (data or	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:01
4	L4	14858	(window\$4 or limit\$1 or range\$1) near10 ((around\$1 or surround\$3 or within) near3 (object\$3 or obstacle\$1 or vehicle\$1))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:03
5	L5	615	(track\$3 or determin\$3 or obtain\$3 or trac\$3) near10 (((current or present) near3 (position\$2 or location)) near5 (object\$1 or obstacle\$1))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:04
6	L6	8	("6122040" "6018308" "5635844" "6198426").pn.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:04
7	L7	50691	(monitor\$3 or surround\$4 or path or neighbor\$5) near5 vehicle\$1	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
8	L8	1968	(radar or scan\$4) near10 ((object\$1 or obstacle\$1 or surround\$5) near5 vehicle\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
9	L9	1639	((radar or scan\$4) near5 (object\$1 or obstacle\$1 or surround\$5)) near10 vehicle\$1	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
10	L10	25134	(radar or scan\$4) near10 (electromagnetic or wave\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
11	L11	7560	((reflect\$3 or bounc\$3) near5 (electromagnetic or wave\$1)) near10 (object\$1 or surround\$4 or obstacle\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
12	L12	4445	(distance\$1 or interval\$1) near10 (vehicle\$1 near5 (object\$1 or obstacle\$1 or surround\$5))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
13	L13	1014736	(determin\$5 or recogni\$5 or detect\$3 or obtain\$3) near5 (distance\$1 or position\$1 or speed\$1 or velocit\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
14	L14	51618	(determin\$5 or recogni\$5 or detect\$3 or obtain\$3) near5 (relative near3 (position\$1 or speed\$1 or velocit\$3))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
15	L15	43794	(determin\$5 or recogni\$5 or detect\$3 or obtain\$3) near10 ((rate or change) near3 (position\$1 or speed\$1 or velocit\$3))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
16	L16	139403	(detect\$3 or sens\$3) near3 (object\$1 or obstacle\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
17	L17	1505	(radar or scan\$4) near5 (detection near3 (point\$1 or data))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
18	L18	6879	(estimat\$3 or calculat\$3 or project\$3 or predict\$3) near5 ((position\$1 or location\$1) near3 (object\$1 or obstacle\$1))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
19	L19	107711	(window\$1 or range\$1 or limit\$1) near10 (object\$1 or obstacle\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05
20	L20	25770	(track\$3 or (present or current) near3 (position\$2 or location\$2)) near5 (object\$1 or obstacle\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	2004/05/25 07:05